Computational Ocean Acoustics (Ray Theory)

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NTNU

April 27, 2015

• Introduction.

- Mathematical Derivation.
- Mathematical properties.
- WKB method.
- Wavenumber integration technique .

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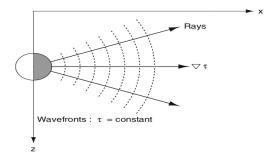
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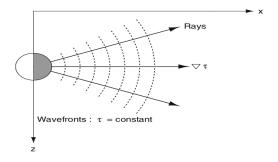
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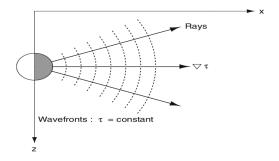
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• Ray is characterized by the angle and trajectory.

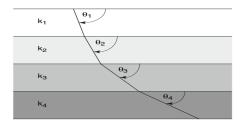


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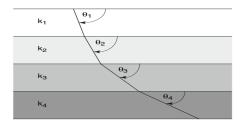
• Ray angle can be found using snell's law.

$$k(z_i)\cos\theta(z_i) = k(z_{i+1})\cos\theta(z_{i+1})$$

• The ray trajectory can be found using the figure above

$$\frac{dr}{dz} = \cot\theta(z)$$
 and $r(z) = \int_{z_0}^{z_r} \cot\theta(z) dz$

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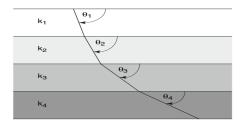


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Ray series solution of wave equation

• Starting with helmholtz equation in Cartesian coordinates

$$\nabla^2 p + \frac{\omega^2}{c^2(x)} p = \delta(x - x_0)$$

• In the ray theory, the solution will be of the ray series form

$$p(x) = e^{i\omega\tau(x)} \sum_{j=0}^{\infty} \frac{A_j(x)}{(i\omega)^j}$$

• Taking the derivative and computing the divergence we have

$$\nabla^2 p = e^{i\omega\tau} [-\omega^2 |\nabla\tau^2| + i\omega\nabla^2\tau] \sum_{j=0}^{\infty} \frac{A_j}{(i\omega)^j} + e^{i\omega\tau(x)} \left\{ 2i\omega\nabla\tau \cdot \sum_{j=0}^{\infty} \frac{\nabla A_j}{(i\omega)^j} + \sum_{j=0}^{\infty} \frac{\nabla^2 A_j}{(i\omega)^j} \right\}$$

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• Eikonal equation is used to trace the acoustic rays and find the phase of the pressure field.

$$|\nabla \tau|^2 = \frac{1}{c^2(x)}$$

- Ray coordinates are used to linearize the differential equation.
- Considering ∇τ perpendicular to the wavefront, the ray trajectory x(s) is defined as.

$$\frac{dx}{ds} = c\nabla\tau$$
 and $\left|\frac{dx}{ds}\right|^2 = c^2|\nabla\tau|^2$

$$\frac{d}{ds}\left(\frac{1}{c}\frac{dx}{ds}\right) = -\frac{1}{c^2}\nabla c$$

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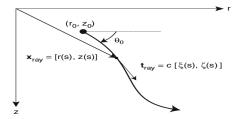
$$\frac{d}{ds}\left(\frac{1}{c}\frac{dx}{ds}\right) = -\frac{1}{c^2}\nabla c$$

• In cylindrical coordinates (*r*, *z*), these ray equations will be given in first-order form as.

$$\frac{dr}{dz} = c\xi(s), \qquad \qquad \frac{d\xi}{ds} = -\frac{1}{c^2}\frac{\partial c}{\partial r} \\ \frac{dz}{ds} = c\zeta(s) \qquad \qquad \frac{d\zeta}{ds} = -\frac{1}{c^2}\frac{\partial c}{\partial z}$$

• In order to completely specify the equation, the initial conditions are used to specify the source position (r_0, z_0) and take-off angle θ_0 .

$$r = r_0, \qquad \xi = -\frac{\cos\theta_0}{c(0)}$$
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Phase of the pressure field

• • The phase of the pressure field is obtained from the eikonal equation in ray coordinate system

$$\nabla \tau \cdot \nabla \tau = \frac{1}{c^2}$$
$$\nabla \tau \cdot \frac{1}{c} \frac{dx}{ds} = \frac{1}{c^2}$$
$$\frac{d\tau}{ds} = \frac{1}{c}$$

• This is the eikonal equation in ray coordinate *s*. Linearizing the PDE we have

$$\tau(s) = \tau(0) + \int_0^s \frac{1}{c(s')} ds'$$

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• The amplitude of the pressure field is obtained from the transport equation in ray cooridinate system

$$2\nabla \tau \cdot \nabla A_0 + (\nabla^2 \tau) A_0 = 0$$

• Rays are defined as being perpendicular to the wavefront so

$$\frac{2}{c}\frac{dx}{ds}\cdot\nabla A_0 + (\nabla^2\tau)A_0 = 0$$

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• $\nabla^2 \tau$ can be calculated using the Jacobian

$$\nabla^2 \tau = \frac{1}{J} \frac{d}{ds} \left(\frac{J}{c} \right)$$

• Putting this value and integrating we have

$$A_0(s) = A_0(0) \left| \frac{c(s)J(0)}{c(0)J(s)} \right|^{1/2}$$

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$$\tau(s) = \tau(0) + \int_0^s \frac{1}{c(s')} ds'$$
$$A_0(s) = A_0(0) \left| \frac{c(s)J(0)}{c(0)J(s)} \right|^{1/2}$$

- Initial condition is found using the canonical problems method.
- Considering the point source in an infinite homogenous media as canonical problem

$$p^0(s) = \frac{e^{i\omega s/c_0}}{4\pi s}$$

- where *s* is the distance from the source and $c_0 = c|_{s=0}$.
- The amplitude and the phase associated with the solution are.

$$A^{0}(s) = \frac{1}{4\pi s} \qquad \tau^{0}(s) = \frac{s}{c_{0}}$$
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- For A_0 the initial condition is computed for $A_0(0)|J(0)|^{1/2}$
- The Jacobian in the homongenous medium turns out to be

$$J(s) = -s^2 cos\theta_0$$

• The initial condition will be

$$\lim_{s \to 0} A(s) |J(s)|^{1/2} = \frac{1}{4\pi} |\cos\theta_0|^{1/2}$$

$$p(s) = \frac{1}{4\pi} \left| \frac{c(s)\cos\theta_0}{c(0)J(s)} \right|^{1/2} e^{i\omega \int_0^s \frac{1}{c(s')} ds'}$$

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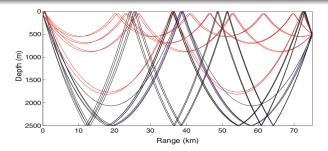
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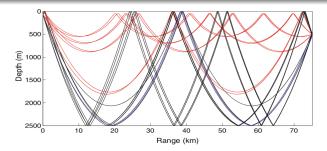


• The intensity at any point in the pressure field is the sum of the contribution of each eigen ray

$$p^{(C)}(r,z) = \sum_{j=1}^{N(r,z)} p_j(r,z)$$

• The number of contributing eigenrays varies with the range and source-receiver position.

Coherent Transmission Loss

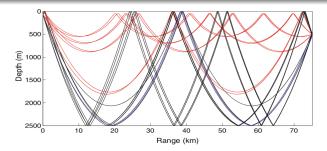


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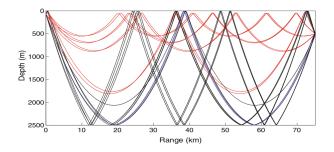


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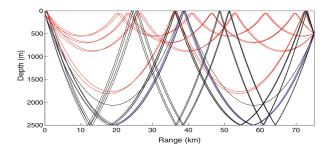
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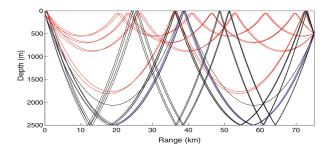
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- At longer ranges, there can be many rays with many top and bottom interactions.

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- Ray methods are used for high frequency problems.
- At high frequencies, the pressure field is very sensitive to the environmental factors and detailed knowledge of the environment is not available all the time.
- In this case incoherent calculations are considered where the phase of the pressure associated with each ray is ignored.

$$p^{(I)}(r,z) = \left[\sum_{j=1}^{N(r,z)} |p_j(r,z)|^2\right]^{1/2}$$

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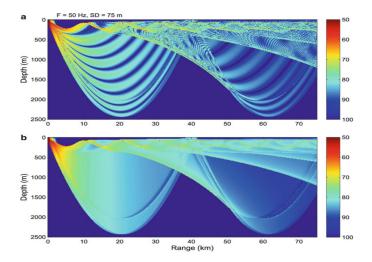
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Coherent Vs Incoherent Transmission Loss



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- Informal and partially empirical based techniques.

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- Appropriate for directional sources.

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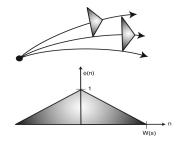
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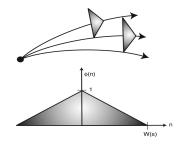
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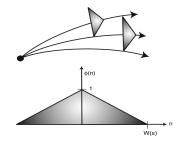


- How to calculate the field in between the rays ?
- Interpolate from the ray grid by constructing a beam around each ray.
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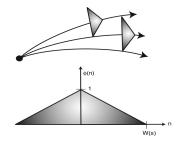


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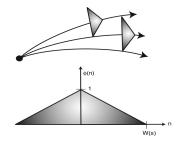
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- Complicates the process of finding the eigenrays.
- To simplify, we can neglect the imaginary part of the sound speed and add a loss corresponding to the path length of the real rays.
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$$c_0^2(\nabla\tau_0)(\nabla\tau_1) + c_0c_1|\nabla\tau_0|^2 = 0$$

• After some manipulations we have .

$$\tau_1(s) = -\int_0^s \frac{c_1(s')}{c_0^2(s')} ds'$$

• If the perturbation is due to loss α , it introduces an imaginary part in the sound speed.

$$ic_i \simeq -i\alpha \frac{|c_r^2|}{\omega}$$

$$p(s) = \frac{1}{4\pi} \left| \frac{c(s)cos\theta_0}{c(0)J(s)} \right|^{1/2} e^{i\omega \int_0^s \frac{1}{c(s')}ds'} e^{-i\int_0^s \alpha(s')ds'}$$

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- Application of ray theory to one dimensional problems.
- The derivation of WKB approximation proceeds the same way except all vectors equations becomes scalar with single variable *z*.

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Related Techniques

WKB Method

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$$\tau(z) = \pm \frac{1}{\omega} \int k_z(z) dz$$

• Using this result, the first transport equation becomes

$$2k_z(z)\frac{dA_0}{dz} + \frac{dk_z}{dz}A_0 = 0$$

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$$A_0(z) = \frac{B}{\sqrt{k_z(z)}}$$

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• In the absence of a source, the total field can be represented as a combination of an upgoing and downgoing canonical wave.

$$\phi(r,z) = \int_0^\infty \left[A^- e^{-ik_z z} + A^+ e^{-ik_z z} \right] J_0(k_r r) k_r dk_r$$

 To evaluate the boundry conditions vertical displacement w(r, z) and normal stress σ_{zz} is used.

$$w(r,z) = \frac{\partial \phi}{\partial z}$$
 $\sigma_{zz} = -\rho \omega^2 \phi(r,z)$

• In the presence of a source we have to add the contribution of $\hat{\phi}(k_r, z)$.

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